

Template for Abstract – 2016 Israel Robotics Conference

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This is a sample document of abstract for the 2016 Israel Robotics Conference (ICR2016). The abstract should be submitted in **English**. All text should be in font Times New Roman. Title should be 12pt size boldface type. Authors' names should be 12pt size normal type. Affiliations should be 10pt size, and the main text should be 11pt size with spacing of 1.5 lines. Page margins should coincide with this template (2.5 cm top and bottom, 3 cm left and right).

The main text should contain up to 2000 characters and may include multiple paragraphs, but no sections and titles. Up to three figures or pictures with numbering and captions may be included (see Figure 1 as an example). A short bibliographic list may be included at the end of the document with font size 9pt and [IEEE referencing style](#). Referencing should appear within the text with numbers such as [1]; [2], [3]; and [1]-[3]. The total length of the abstract is limited to a single A4 page. Abstracts in final form should be submitted as MS-WORD document. **Final camera ready submission deadline: January 31st, 2016**. Additional submission of full papers is optional, with the same submission deadline. The papers should be 3 to 6 pages long in two columns, formatted according to IEEE template for conference papers, which can be found at: www.ieee.org/web/publications/pubservices/confpub/AuthorTools/conferenceTemplates.html

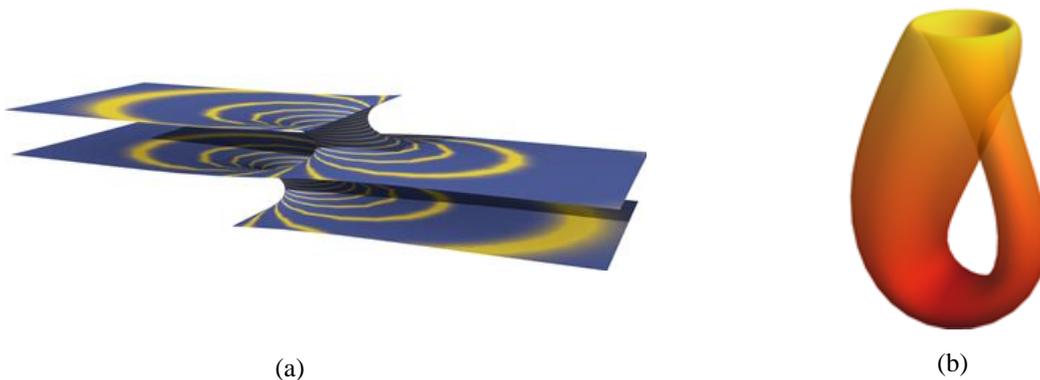


Figure 1. (a) Section of Riemann's minimal surface. (b) A two-dimensional representation of the Klein bottle immersed in three-dimensional space.

References:

- [1] B. Klaus and P. Horn, *Robot Vision*. Cambridge, MA: MIT Press, 1986.
- [2] L. Stein, "Random patterns," in *Computers and You*, J. S. Brake, Ed. New York: Wiley, 1994, pp. 55-70.
- [3] S. P. Bingulac, "On the compatibility of adaptive controllers," in *Proc. 4th Annu. Allerton Conf. Circuit and System Theory*, New York, 1994, pp. 8-16.